

# NONPROVISIONAL PATENT APPLICATION

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## BOX PATENT APPLICATION

### NONPROVISIONAL APPLICATION TRANSMITTAL RULE §1.53(b)

Director of the U.S. Patent and Trademark Office  
Washington, D.C. 20231

Sir:

Transmitted herewith for filing under 37 C.F.R. §1.53(b) is the nonprovisional patent application

For (Title): A NAVIGATION SYSTEM AND A MEMORY MEDIUM

By (Inventors): Hironari IWASAKI, Shogo ITO, Kazuhiro IKEDA, Koji KATO, Yasuyuki TAKEDA

- ☒ Formal drawings (Figs. 1-15; 15 sheets) are attached.
- ☐ A Declaration and Power of Attorney is filed herewith.
- ☐ An assignment of the invention to \_\_\_\_\_ is filed herewith.
- ☐ An Information Disclosure Statement is filed herewith.
- ☐ A statement to establish small entity status under 37 C.F.R. §§1.9 and 1.27 is filed herewith.
- ☐ A Preliminary Amendment is filed herewith.
- ☐ Please amend the specification by inserting before the first line the sentence --This nonprovisional application claims the benefit of U.S. Provisional Application No. \_\_\_\_\_, filed \_\_\_\_\_--
- ☒ Priority of foreign application(s) No. JP HEI 11-224117 filed August 6, 1999 in Japan is claimed (35 U.S.C. §119).
- ☐ A certified copy of the above corresponding foreign application(s) is filed herewith.
- ☒ The filing fee is calculated below:

#### CLAIMS IN THE APPLICATION AFTER ENTRY OF ANY PRELIMINARY AMENDMENT NOTED ABOVE

FOR:	NO. FILED	NO. EXTRA
BASIC FEE		
TOTAL CLAIMS	15 - 20	= 0*
INDEP CLAIMS	5 - 3	= 2*
<input type="checkbox"/> MULTIPLE DEPENDENT CLAIMS PRESENTED		

\* If the difference is less than zero, enter "0".

#### SMALL ENTITY

RATE	FEE
	\$ 345
x 9 =	\$
x 39 =	\$
+130 =	\$
TOTAL	\$

#### OTHER THAN A SMALL ENTITY

RATE	FEE
	\$ 690
x 18	\$-----
x 78	\$156
+260	\$-----
TOTAL	\$846

- ☒ Check No. 110845 in the amount of \$846.00 to cover the filing fee is attached. Except as otherwise noted herein, the Director is hereby authorized to charge any other fees that may be required to complete this filing, or to credit any overpayment, to Deposit Account No. 15-0461. Two duplicate copies of this sheet are attached.
- ☐ This application is entitled to small entity status. DO NOT charge large entity fees to our Deposit Account.

Respectfully submitted,

James A. Oliff  
Registration No. 27,975

Dermott J. Cooke  
Registration No. 41,685

JAO:DJC/cmm

### **Inventor Information**

Inventor One Given Name:: Hironari  
Family Name:: IWASAKI  
Name Suffix::  
City of Residence:: Okazaki  
State or Prov. of Residence:: Aichi  
Country of Residence:: Japan  
Inventor Two Given Name:: Shogo  
Family Name:: ITO  
Name Suffix::  
City of Residence:: Okazaki  
State or Prov. of Residence:: Aichi  
Country of Residence:: Japan  
Inventor Three Given Name:: Kazuhiro  
Family Name:: IKEDA  
Name Suffix::  
City of Residence:: Okazaki  
State or Prov. of Residence:: Aichi  
Country of Residence:: Japan  
Inventor Four Given Name:: Koji  
Family Name:: KATO  
Name Suffix::  
City of Residence:: Okazaki  
State or Prov. of Residence:: Aichi  
Country of Residence:: Japan  
Inventor Five Given Name :: Yasuyuki  
Family Name:: TAKEDA  
Name Suffix::  
City of Residence:: Okazaki  
State or Prov. of Residence:: Aichi  
Country of Residence:: Japan

### **Correspondence Information**

Name Line One:: Oliff & Berridge PLC  
Address Line One:: P.O. Box 19928  
City:: Alexandria  
State or Province:: VA  
Postal or Zip Code:: 22320  
Telephone:: (703) 836-6400  
Fax:: (703) 836-2787  
Electronic Mail:: commcenter@oliff.com

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### **Continuity Information**

>This application is a::  
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### **Prior Foreign Applications**

Foreign Application One:: JP HEI 11-224117  
Filing Date:: August 6, 1999  
Country:: Japan  
Priority Claimed:: yes  
Foreign Application Two::  
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Priority Claimed::  
Foreign Application Three::  
Filing Date::  
Country::  
Priority Claimed::

## A NAVIGATION SYSTEM AND A MEMORY MEDIUM

BACKGROUND OF THE INVENTION1. Field of Invention

This invention relates to a navigation system and memory medium that  
5 improve the varieties and efficiencies of searches for a register point within an area  
such as a vicinity search, an area designated search and so on.

2. Description of Related Art

Figure 14 is a diagram describing a prior known vicinity search process.  
When starting the vicinity search process, objects existing within a predetermined  
10 limit are searched. The search is executed by searching for register point data (object  
data) by each area block within the predetermined limit. Further, a hotel may be  
selected, for example, as a category (genre) to be searched. Hotels are then sorted  
from the searched register point data and displayed as a list according to their distance  
from a common origin. Of course, a list can also be displayed by sorting distances  
15 only without selecting a category.

Figure 15 is a diagram describing a search process for displaying a list of  
categories by designating areas. By selecting areas according to designated  
categories, for example an administrative unit, then a list of categories common to  
each area is displayed.

20 In accordance with a prior known periphery search process, in which a vehicle  
travels along a specified route guidance, if a stop for meals or shopping is desired,  
then a user may immediately search for desired facilities by using the navigation  
system. In such a case, designated categories (genres) that exist within a  
predetermined limit from a present position (e.g., within 10 km) are displayed in a list.  
25 However, if a present position is located near a border between Fukuoka-Prefecture  
and Yamaguchi-Prefecture, for example, then facilities existing in Fukuoka and  
facilities existing in Yamaguchi are combined in the list without regard to the types of  
roads needed to travel to reach the facilities when displayed. Because of this, a user is  
unable to locate facilities accessible by traveling exclusively on normal roads. Rather,  
30 facilities to which the user can go only by traveling on tool roads, i.e., non-normal  
roads, are also displayed. As a result, a user is likely to select those facilities on  
non-normal roads by mistake.

Further according to the prior search process, when a category is selected, register point data is displayed in a list only after determining whether each register point data in each area block corresponds to the category selected by the user. This requires a lot of time as all the register point data have to be checked even if the corresponding category does not exist in some area blocks. Moreover, because each area has a fixed list of common categories, a problem arises in that even absent or vacant categories are displayed in a list in some areas.

### SUMMARY OF THE INVENTION

The invention conducts a search by designating register point data belonging to the same area when making the vicinity search. The invention further conducts a variety of searches when making the vicinity search. Still further, the invention reduces searching time when making the vicinity search and displays a category list by designating an area in a way corresponding to the area.

As described above, according to the invention, because vicinity search data is provided with area data, such as country names etc. of the register points, a vicinity search can be made by specifying objects in the same area, thereby permitting various searches to be made.

Further, when register points are searched by hierarchically limiting categories, the time required for making the vicinity search can be reduced by obtaining information regarding the presence and absence of the register points belonging to category items in the lower hierarchy categories. Further, when searching categories by designating an area, categories with no register point data in the areas are not displayed as only category items with register point data existing are displayed in a list. Thus, the list can be displayed in a way that accurately corresponds to the area.

The navigation system and memory medium of the invention comprises an input means for inputting information to conduct a vicinity search including at least information regarding a reference position of the vicinity search, a display means for displaying a search result, an information storage means for storing at least the vicinity search data and a search means for making the vicinity search on the basis of data input by the input means and stored in the information storage means, wherein the vicinity search data includes at least area information and the search means conducts the vicinity search on the basis of the area information to which register

points belong and outputs the search result to the display means. The invention includes area information wherein the area information is country information, district information, prefectural information or municipality information. The navigation system of the invention further comprises an input means for inputting information necessary to conduct the register point search within the area, a display means for displaying the search result, an information storage means for storing data necessary for at least the register point search, a search means for making the register point search within the area on the basis of information input by the input means and data stored on the information storage means, wherein the register point search data within the area include category information to which flags are associated for representing whether register point data are present or absent, and the search means searches for register point data by referring to the flags. The navigation system of the invention further conducts the register point search within the area of the vicinity search and the search means searches for register point data on the basis of information regarding the reference position input by the input means, wherein the register point data is controlled by dividing each vicinity into an area or block, and category information is stored on the basis of each area or block such that a flag representing whether register point data are present or absent as category information of each area or block. Thus, the register point data are controlled on the basis of each category and a flag representing whether the data are present or absent, is given as category information of each area or block, wherein a data structure of category information is hierarchical and flags are given representing whether register point data exist in categories of the lower hierarchy before proceeding to a category of the upper hierarchy. The register point search within an area is the area designated search and the search means searches for register point data on the basis of information regarding an area input by the input means. The area may be a country or an administrative unit, or the like.

The invention further provides a memory medium that stores a program for conducting a vicinity search and for displaying a search result, wherein the conducting of the vicinity search includes searches for area information on the basis of the input reference position for the vicinity search. The memory medium further stores a program for searching for register points within an area on the basis of input data and stored data and for displaying a search result, wherein the step for searching the register points within the area makes a search by referring to flags given to categories

in an area that represent whether register point data are present or absent in the area. Further the memory medium of the invention searches for register point data within a predetermined area on the basis of each category and stores a flag representing the existence or absence of register point data based upon either the searched register point data or the category information data for displaying categories.

#### BRIEF DESCRIPTION OF THE DRAWINGS

Figure 1 is a diagram showing an example of the composition of a vehicle navigation system according to the invention;

Figure 2 is a diagram showing an example of vicinity search data structure according to the invention;

Figure 3 is a block diagram describing an example of vicinity search according to the invention;

Figure 4 is a diagram showing an example of a list in which a plurality of register points is searched by category + name and sorted according to distance;

Figure 5 is a diagram showing an example of a list in which a plurality of register points is searched by name and sorted according to distance;

Figure 6 is a diagram showing an example of a list in which a plurality of register points is searched by category + name + country and sorted according to distance;

Figure 7 is diagrams showing alphabetical input screens;

Figure 8 is a diagram showing an example of register point data structure when inputting alphabetically object names;

Figures 9(a), (b), (c) and (d) are diagrams showing respective genre data structure according to respective area blocks used when making a vicinity search within a predetermined limit;

Figure 10 is a diagram describing access to data when making a vicinity search;

Figure 11 is a flowchart describing a searching method in category selection;

Figure 12 is a flowchart describing a category selection process;

Figure 13 is a flowchart describing a display screen of selected categories;

Figure 14 is a flowchart describing a vicinity search process according to a related approach; and

Figure 15 is a flowchart describing a search process so as to display a list of categories by designating areas.

### DETAILED DESCRIPTION OF PREFERRED EMBODIMENTS

Embodiments of the invention will be described below with reference to the drawings. Figure 1 is a diagram showing an example of a navigation system according to the invention. The invention is composed of an input unit 1 for inputting information regarding route guidance; a present position detecting unit 2 for detecting information regarding a present position of a vehicle; an information storage unit 3 for storing therein navigation data required for calculation of routes, display/audio guidance data required for route guidance, programs (application and/or OS) and the like; a central processing unit 4 for providing control over the entire system; an information transmitter/receiver 5 for transmitting and receiving information regarding the present position, and an output unit 6 for outputting information regarding route guidance.

The input unit 1 is provided with functions for inputting a destination and instructing the central processing unit 4 to execute navigation processing in conformity with a driver's intention. As the means for attaining such functions, a remote controller, such as a touch switch, a jog dial or the like, is used for inputting a destination in the form of telephone coordinates on a map and for requesting route guidance. Further, the invention is provided with a unit for performing the interaction by voice input, which functions as a voice input unit. There may also be added a record card reader for reading data recorded in an IC card or a magnetic card. Furthermore, there may be added a data communication device to provide data communications between information sources, such as an information center for accumulating therein data necessary for navigation, via communication links upon the driver's request. A portable style electronic device having map data, destination data, and data of a simple frame map and a building shaped map and the like may be added as well.

The present position detecting unit 2 receives information on the present position of the vehicle by using the Global Positioning System (GPS), an absolute direction sensor, such as a geomagnetic device for detecting the travel direction of the vehicle, a relative direction sensor, such as a combination of a steering sensor and a gyro sensor, for detecting the relative travel direction of the vehicle, and a distance



sensor for detecting the travel distance according to a number of revolutions of a wheel, for example.

The information memory device 3 is an external storage device in which programs and data for navigation are stored. The information memory device 3 may be, for example, a CD-ROM, a DVD-ROM, or the like. The programs stored therein include a program for processing the route search. Such a processing program is shown in Figures 11 as a flowchart and includes a program for performing guidance in the interactive manner by the voice input and necessary data therefor, and a program for performing the voice output control necessary for the voice guidance and necessary data therefor. The data to be stored therein are composed of files, such as map data, search data, guidance data, map matching data, destination data, register point data, road data, genre data, landmark data and the like, wherein all the data necessary for navigation are stored. In addition, the invention can be applied to a system in which the CD-ROM contains only the stored data and the central processing unit contains the programs.

The central processing unit 4 comprises a CPU for performing various calculation processing; a flash memory for reading and storing the programs from the CD-ROM of the information memory unit 3; a ROM containing a program (or program reading means) for checking and updating the programs contained in the flash memory; a RAM for temporarily storing the searched route guidance information, such as the point coordinates of a set destination, a road name code No., or the like or data under the calculation processing. The central processing unit 4 further provides a voice processor for processing the voice input from the input unit 1 and for synthesizing and transforming a voice, a phrase, a sentence, a sound, or the like, into an analog signal and outputting it to the speaker. The CPU 4 further provides a communication interface for transferring the input/output data, a sensor input interface for receiving the sensor signal of the present position detecting unit 2, and a clock for writing the date and time as an internal diagnosis information. In addition, the program for an updating process may be stored in an external memory unit.

The programs according to the invention and the other programs for executing navigation may be wholly stored in a CD-ROM as an external memory medium, or they may be partially or wholly stored in the ROM. The data and programs stored in

the external memory medium are input as external signals to the central processing unit 4 of the navigation system and processed by calculation so that various navigation functions are realized.

As described above, the navigation system includes a flash memory having a relatively large capacity for reading programs from the CD-ROM of the external memory unit, and a ROM having a small capacity that contains a program (or program reading means) for starting the CD-ROM. The flash memory is the non-volatile memory means for maintaining the stored information even if the power is turned off. As an initial processing of the CD-ROM, the programs stored in the ROM are initiated to check the programs stored in the flash memory and to read the disc managing information etc., stored in the CD-ROM of the information storage unit 3. The loading (or updating) operation of the programs is executed by determining that information and the state of the flash memory.

The information transmitter-receiver 5 comprises a GPS receiver for obtaining information by making use of the satellite navigation system (GPS), and a VICS receiver for obtaining information via FM multi-channels, electric beacons, light beacons, etc. A data transmitter is exemplified by a portable telephone, a personal computer, or the like for exchanging the information with an information center (e.g., ATIS), other vehicles, and the like.

The output unit 6 is provided with functions for outputting voice/display guidance information required by the driver, and for outputting the navigation data processed in the CPU 4 to the printer. As means for realizing these functions, the output unit comprises a display for displaying input data on a screen or for displaying a route guidance screen, a printer for outputting the data processed in the CPU 4 or the data stored in the information memory unit 3 to the printer, a speaker for outputting route guidance by voice, and the like.

The display includes a color CRT or liquid-crystal display device, for example, and display screens show enlarged intersections, destination names, times, distances, travel directions, character images, and the like on the basis of map data or guidance data processed by the central processing unit 4. The image data transmitted to the display are binary image data (bitmap data) so that not only a communication line used for a serial communication is used but also other communication lines can be used for the transmission. As a result the data are not transmitted through a

special-purpose signal. The display is provided with a memory for temporarily storing the bitmap data. In addition, the display is mounted in the instrument panel of the vehicle, in the vicinity of the driver's seat, so that the driver is able to confirm the present position of the vehicle and conveniently obtain information on a next route to follow. The display may be composed so that points or roads, etc., can be input by touching or tracing the screen with a tablet, a touch panel, a touch screen etc., a detailed description of which is omitted.

A flow of the entire navigation system according to the invention is hereafter described. The route guidance program is initiated upon reading the program of the information processing unit 3 to the central processing unit 4, after which, a vehicle's present position is detected by the present position detecting unit 2. Then a vicinity map with the vehicle's present position being its center is displayed with a name of the present position. Thereafter, a destination is determined using an object name, such as a place name, a facility name, a telephone number, an address, a register point, a road name or the like, and a route search from the vehicle's present position to the destination is executed. When a route is determined, route guidance/display is repeated until the vehicle arrives at the destination, with the vehicle's changing present position having been traced throughout the route by the present position-detecting unit 2. If a new input is executed when the vehicle stops on the way before arriving at the destination, a search area is established on the basis of the new input and a new search is conducted for the new area. At the same time, the route guidance is repeatedly executed until the vehicle arrives at the destination.

Figure 2 is an example of a vicinity search data structure. In the vicinity search, wherein the user inputs categories (genres), a limited number of coordinates and other search references are deemed register points existing within a limit designated according to a reference position selected by the user or otherwise determined automatically by the position detecting unit 2, whereby the detected vehicle's present position is its center. The register points are searched, according to the designated search reference and are selected and weighted in response to the designated research reference. Priorities are given thereto and they are displayed in the order of the priorities.

The vicinity search data consist of data (files) on the basis of each area block, wherein file numbers showing the amount of data are stored in the header record.

Information regarding each block is stored as coordinate data. Information regarding the location of each data is deemed allocation data. The genre allocation table contains flags representing the presence or absence of category information, the classifications of categories, and the number of register point data. The register point data contain information of the longitude and latitude coordinates thereof, offset names indicative of locations of name data of the register points, and information about a country to which these points belong. The text pool stores therein name data (character strings) of the register points.

Figure 3 is a block diagram describing an example of a vicinity search according to the invention. As shown in Figure 2, vicinity data stores category information, coordinate information of each register point, country information and register point names. Therefore, the vicinity search is made within a predetermined limit by designating any one of categories, countries, names or a combination thereof. Thus register points are displayed in a list based upon their location relative to the reference location.

Figure 4 shows an example of a search made by a category and a name and listed according to distances from a common origin. In this example, register points are searched by a combination of the category "HOTEL" and the name "AA". The register points are then sorted in accordance with distances thereof from a common origin. The country name (D) or (F) is given to each hotel, thus showing, in this example, that the vicinity search was made near a border between Germany and France.

Figure 5 shows an example of a search made by name only and sorted in accordance with the distances from a common origin. The register point data having names inclusive of the character string (AA) are displayed in order of the nearest register point to the common origin reference position. The country name (D) or (F) is given to each register point data as well, which indicates that the vicinity search is again made near the border between Germany and France.

Figure 6 shows an example of a search made by the combination of a category, a name and a country, wherein the search results are sorted in accordance with distances from a common origin. The register point data are searched by the category "HOTEL", the name "AA" and the country "GB". Upon completion of the search the

country information is given and hotels are displayed in a list in order of location relative to the common origin reference position.

Other than the above examples, a search may also be made by any of several combinations, such as by name and a country, a category and a country, just a category, just a name or the like, to produce a list sorted in accordance with distances from the common origin reference position. As described above, if a name can be input, a data search can be made so that only corresponding items are displayed on a list. Further, the vicinity search can be made by designating countries. For example, if a search is made near a border in Europe, register points can be sorted in accordance with respective countries and information of respective countries can be therefore searched. As a result, the search can be made in a variety of way to meet a driver's demand.

Next, an example of name input processing in the vicinity search is described.

Figure 7 shows an alphabetical input screen, wherein a first letter of the name "A" is input and a second letter of the name "B" is input. Thereafter a display indicates that a following letter or number is limited to the highlighted "B, E, H, J, M, O, R, U, Y, 3,4,5,6,7" characters. At the same time, a remainder list number is displayed as 1234. At this point in the processing, when a "LIST" key on the screen is pressed, all the register points having the first 2 letters beginning as "A B", are displayed on a list. In the figure, the list highlights "ABCDEFG" as a target register point that can be selected and input with a key operation, a remote control operation or the like. If the remainder list number is large, making it difficult to find a target name in the list on the display screen, increasing the input characters results in less corresponding items in the list. Thus, it is the goal to select a destination name displayed in the list when the remainder number becomes small. In addition, if the character input is carried out until the remainder number shows 1, the remaining name is automatically selected and input with the key operation. The character input is not only executable from the touch panel but also it may be input by voice, if a voice input unit is provided. Further, a name input can be made in the same way as above by using the Japanese phonetic symbols rather than westernized alphabetic inputs.

Figure 8 shows an example of a register data structure when a destination is input by alphabetical input, wherein all the register names having the beginning letter "B" and the second letter "A" are BADAPOZ, BANDANAH, BAIKAL, BAQUBAH,

BARCELONA, BARSTOW, BASEL, BASTAK, BASILAN. BATH, BATHUEST and BAYERN and all the register names having the beginning of the letter "B" and the second letter "E" are BEITRIDGE, BELFAST, BERLIN, BERN, BERGEN and BERKLEY.

5           Using the data structure of Figure 8, if a user wishes to input "BARCELONA" as a target name, the remainder number of the twelve items discovered is displayed due to input of "BA". The remainder number would be two if further inputting of "BAR" were executed, which would reduce the item found to BARCELONA and BARSTOW. Pressing "LIST" at this stage would show, "BARCELONA" and  
10 "BARSTOW" in the list. Inputting "BARC" instead would result in a remainder number of one as only BARCELONA would remain. Therefore, "BARCELONA" is selected in this latter case and it is not necessary to input all 9 letters composing "BARCELONA".

          In the same manner, if "BERLIN" is set as a target name, the remainder  
15 number of six remains unchanged by inputting "BE" or even further inputting "BER" only reduces this list to four names. Only when inputting "BERL" does the remainder number become one resulting in BERLIN being finally selected. Where only BE or BER is inputted, "BERLIN" may be selected from a list displayed when the user input the list key function to display the remainder number of six items. This, therefore,  
20 completes the entire term of "BERLIN" by inputting only 2 or 3 letters.

          Next, a reduction of searching time in the vicinity search is described.

          Figure 9 shows a category data structure wherein each area block is used for making a search within the predetermined limit in the vicinity search. Figure 9(a) is a register point block data structure in which each block shows a predetermined area  
25 and an administrative unit composed of several blocks. Each block of 1-N is established with categories J1-Jn, with flags representing whether register point data belonging to respective categories exists. For example, in block 2, because category J1 shows a flag representing "0", it means no object exists in that category, and since category J2 shows a flag representing "1," it means at least one object exists in this  
30 category. Thus, the user can discover the presence or absence of objects in each category from the flags. Figure 9(b) shows a register point data structure corresponding to categories in a register point block, wherein names, coordinates, detailed information, etc. are established. Figure 9(c) shows categories and

Figure 9(d) shows a register point data structure corresponding to blocks in a category, wherein each block includes a flag showing the presence or absence of register point data. For example, since block 1 shows a flag representing "1", it means there is register point data in block 1. On the other hand, block 2 shows a flag indicating "0", indicating there is no register point data therein. Each register point data is further described in a data structure of Figure 9(b).

Regarding the vicinity search, a switch over to vicinity search mode is accomplished by selecting the vicinity search on a menu screen of the navigation system. A search limit is set, then register data within the limit are searched and a number of items and list names corresponding thereto are displayed. At this stage, as shown in Figure 9, as the presence or absence of register point data in each category can be judged by giving a flag in a block of one category, register points can be searched effectively. In this case, not only categories given flags representing "presence" are displayed, but also categories given flags representing "absence" may be displayed at the same time provided a distinction between them is apparent. For example, the flags may be displayed in different colors, or categories given flags representing "absence" may be displayed by darkening the tone of a color as a method of distinction.

Further, if flags are given to categories, category data may be a hierarchical structure, wherein flags representing the existence of register point data exist in the lower hierarchy may be given to categories in the upper hierarchy. In this way, when a flag of categories in the upper hierarchy is "0", it is not necessary to search for categories in the lower hierarchy resulting in reduced searching time.

In addition, a predetermined limit in the vicinity search may be set such that the vicinity search occurs only within a predetermined distance from a reference position within a geographical area. The reference position may be a vehicle's present position or the cursor position. Further, the geographical area may be within an administrative area including the vehicle's present position or the cursor position, or it may be within an area prescribed by telephone numbers or postal codes including the present position or the cursor position. Further, an area adjoining the administrative area including the present position or the cursor position may be intended for a searching area. In addition, register points within the geographical area or the predetermined distance are searched according to the above block units.

An area for register point search within the area is within a predetermined limit for the vicinity search and/or a designated area for the area-designated search.

Figure 10 is a diagram describing access to data at the time of vicinity search. A-I are files representing data of area blocks. A mark within a file A shows a present position of the vehicle. Access to the data at the time of vicinity search is executed in the order of the nearest file from the driver (present position), namely A\_B\_C\_.....H\_I as shown with a curved arrow.

Figure 11 is a flowchart describing a search method for a category selection, whereby the search method checks data of each file from a file A in the order of A\_B\_C\_.....H\_I as shown in Fig. 10. If a file is one of the files A through I, then it is checked whether the flags given to categories in each block are "1" or "0". Then the categories of flag "1", namely hotels, restaurants and parking are listed. On the other hand, if all the files are checked, then items of each category are displayed in lists or, "absence" is displayed when the flag represents "0". According to the previous method, all the data are searched on the basis of one item after the user selects a category and if the item belongs to the category selected by a user, it is then displayed in the list. Therefore, all the data must be searched for some area blocks even if the selected category does not exist therein. On the other hand, according to the invention's method, first flags given to each category in a file are checked then items of the category are not checked if the flag is "0" so that searching time can be reduced.

Next is described an area-designated search.

The area-designated search is for searching register points of desired categories within an area. The designated area may be intended for an administrative unit such as a country, a region, a state, a prefecture, a city, a town, a village etc., or for an area prescribed by telephone numbers or postal codes. Further, areas adjoining the designated area may be intended for search areas. Search data has the same data structure as data shown in Figure 9(a) with given flags representing whether register point data exist in each category on the basis of each area block.

Figure 12 is a flowchart describing a category selection process, whereby an area is selected and category data belonging to the area are read. Because flags representing absence or presence are given to category data, categories with no register points are excluded by referring to flags. Therefore, only categories with register points are obtained and displayed in a list.



Figure 13 is a flowchart describing display screens of selected categories, wherein a list of categories is obtained by selecting an area. For example, the area A shows BBB, DDD, EEE, FFF and the area B shows AAA, BBB, GGG, HHH. Thus, only existing categories are displayed in respective lists. In area designated searches

5 according to the previous method, even categories with no register points are displayed in a list in some areas since fixed categories common to each area are displayed in a list (see Fig. 15). However, this problem is avoided in the invention. Further, all the categories may be displayed by making a distinction between the presence and absence of the register points, in addition to displaying only categories

10 with register points in a list.

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WHAT IS CLAIMED IS:

1. A navigation system, comprising:
  - an input means for inputting information necessary to conduct a vicinity search including at least information regarding a reference position;
  - 5 a display means for displaying a search result;
  - an information storage means for storing at least the vicinity search data;
  - a search means for making the vicinity search on the basis of data stored in said information storage means and information input by said input means,
  - 10 wherein said vicinity search data include at least area information, and said search means conduct the vicinity search on the basis of area information to which the register points belong and inputs the search result to said display means.
2. The navigation system according to claim 1, wherein said area information is country information, district information, prefectural information or
  - 15 municipality information.
3. A navigation system, comprising:
  - an input means for inputting information for searching register points within an area or block;
  - a display means for displaying a search result;
  - 20 an information storage means for storing data necessary for at least a register point search; and
  - a search means for searching for register points within the area, wherein said register point search data within the area include category information with flags representing the presence or absence of register point data and said search
  - 25 means search for register point data by referring to said flags.
4. The navigation system according to claim 3, wherein said register point data search within an area is a vicinity search and said search means search for register point data on the basis of information regarding a reference position input by said input means.
5. The navigation system according to claim 3, wherein said register point data are divided into an area or block and controlled such that category information is stored on the basis of each area or block and flags representing the presence or absence of register point data are given as category information of each area or block.

6. The navigation system according to claim 3, wherein register point data are controlled by each category, and flags representing the presence or absence of register point data for an area or block are given in each category.

7. The navigation system according to claim 3, wherein a data structure of category information is hierarchical and flags representing the presence or absence of register point data in categories of the lower hierarchy, are given to a category of the upper hierarchy.

8. The navigation system according to claim 4, wherein a data structure of category information is hierarchical and flags representing the presence or absence of register point data in categories of the lower hierarchy, are given to a category of the upper hierarchy.

9. The navigation system according to claim 5, wherein a data structure of category information is hierarchical and flags representing the presence or absence of register point data in categories of the lower hierarchy, are given to a category of the upper hierarchy.

10. The navigation system according to claim 6, wherein a data structure of category information is hierarchical and flags representing the presence or absence of register point data in categories of the lower hierarchy, are given to a category of the upper hierarchy.

11. The navigation system according to claim 3, wherein said register point search within an area is an area designated search, and said search means conducts a search for register point data on the basis of information regarding the area input by said input means.

12. The navigation system according to claim 11, wherein said area is a country or an administrative unit.

13. A memory medium for a navigational system comprising a program for conducting a vicinity search on the basis of input data and for displaying a search result, wherein the said vicinity search searches for area information on the basis of the input reference position of the vicinity search.

14. A memory medium for a navigational system, comprising:  
a program for searching for register points within an area on the basis of input data and for displaying a search result, wherein the searching of said register

points within the area refers to flags given to category information, representing whether register point data are present or absent in an area.

- 15 A memory medium for a navigational system that searches for register point data within a predetermined area by category and stores flags representing whether register point are present or absent on the basis of each category.
- 5

ABSTRACT OF THE DISCLOSURE

A vicinity search using register point data in a designated area reduces search time. The vicinity search data include at least category information, names of register points and country information. The search device conducts the vicinity search by  
5 specifying any one of category information to which the register points belong, names of the register points and country information, or a combination, by option and display. The search device further uses category information with flags representing the presence and absence of the register point data, whereby the register point data are searched by referring to the flags.

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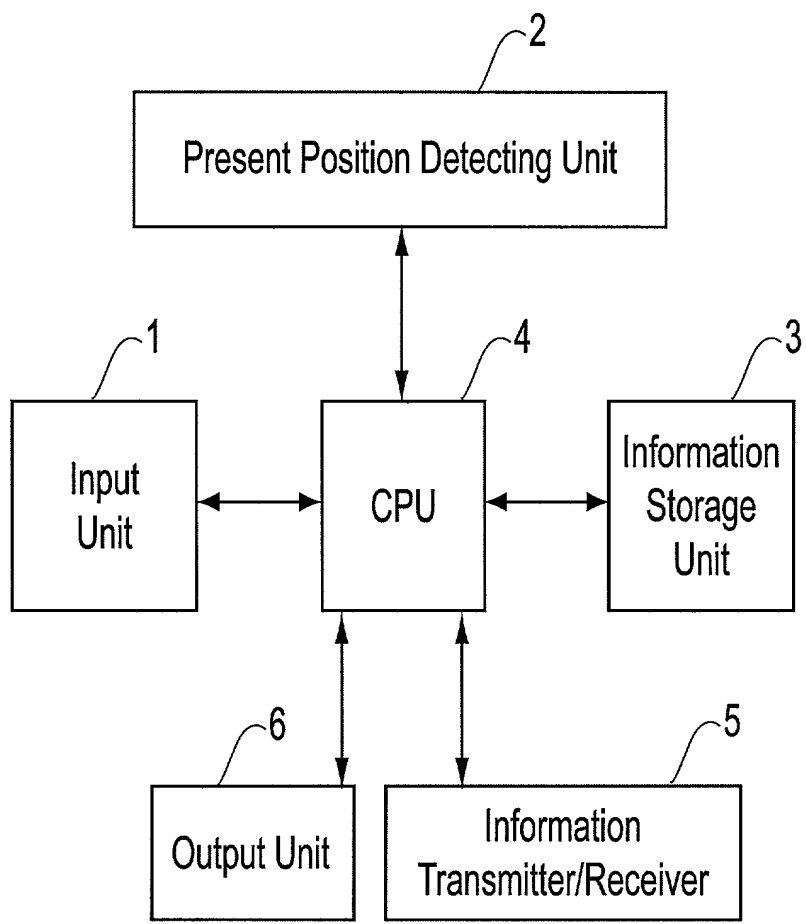


Fig. 1

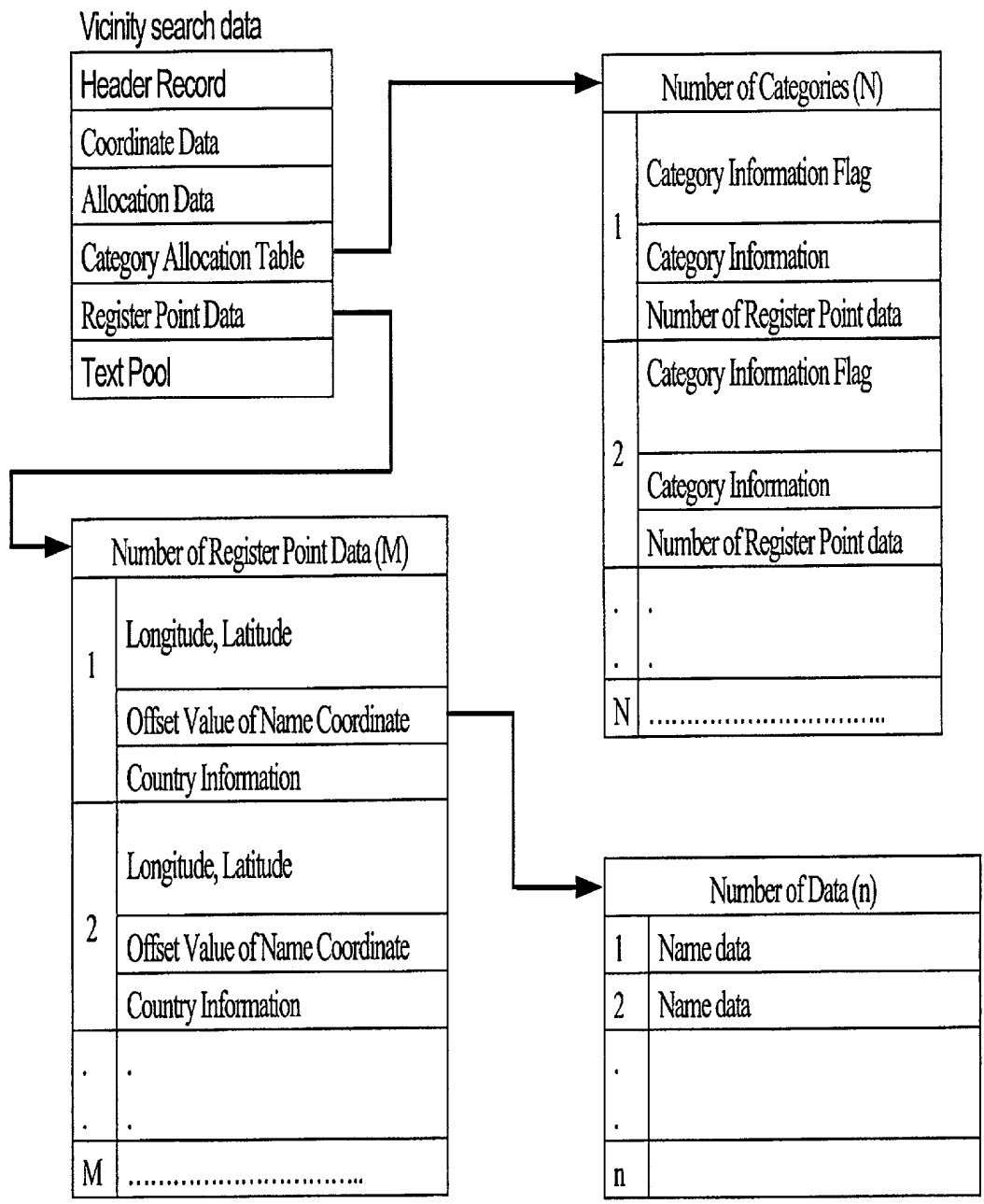


Fig. 2

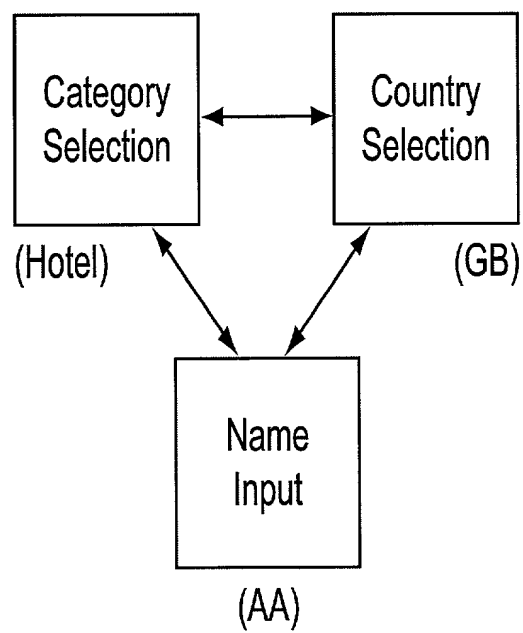


Fig. 3



Category + Name + Distance sort



List

D	<u>Hotel ASSERS INN</u>	0.3 km
F	<u>Hotel ACCEAN NEW HOTEL</u>	1.2 km
D	<u>Hotel AARADEA HOTEL</u>	2.5 km
F	<u>Hotel AACEHN HOTEL</u>	3.5 km
D	<u>Hotel AA YOUTH HOTEL</u>	9.4 km

Fig. 4

Name + Distance sort



List

D	<u>RESTAURANT ASSERS INN</u>	0.3 km
F	<u>PARKING AA NEW PAR</u>	1.2 km
D	<u>Hotel AARADEA HOTEL</u>	2.5 km
F	<u>SHOP AASERS WINERY</u>	3.5 km
D	<u>BAR AA BAR</u>	9.4 km

Fig. 5

Category + Name + Country + Distance sort



List

GB Hotel ASSERS INN 0.3 km

GB Hotel ACCEAN NEW HOTEL 1.2 km

GB Hotel AARADEA HOTEL 2.5 km

GB Hotel AACEHN HOTEL 3.5 km

GB Hotel AA YOUTH HOTEL 9.4 km

Fig. 6

# Alphabet Input Screen

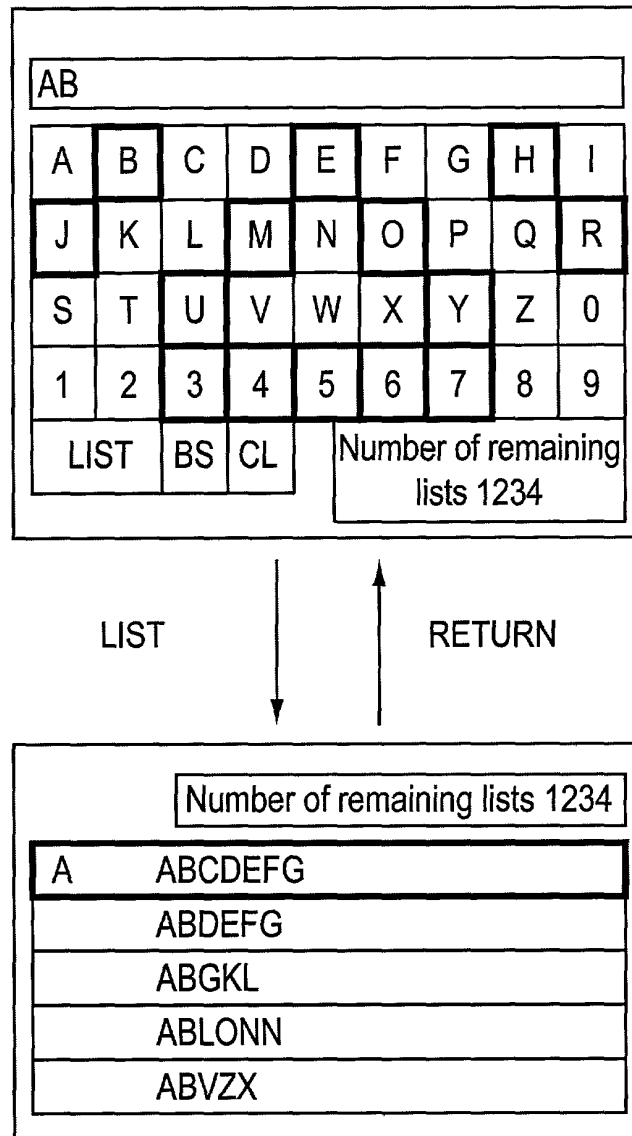


Fig. 7

The first letter of word	Register point name
•	•
•	•
•	•
B	•
•	BADAPOZ
•	BADANAH
•	BAIKAL
•	BAQUBAH
•	BARCELONA
•	BARSTOW
•	BASEL
•	BASTAK
•	BASILAN
•	BATH
•	BATHURST
•	BAYERN
•	•
•	•
•	•
•	BEITBRIDGE
•	BELFAST
•	BERLIN
•	BERN
•	BERGEN
•	BERKLEY
•	•
•	•
•	•
•	•

Fig. 8

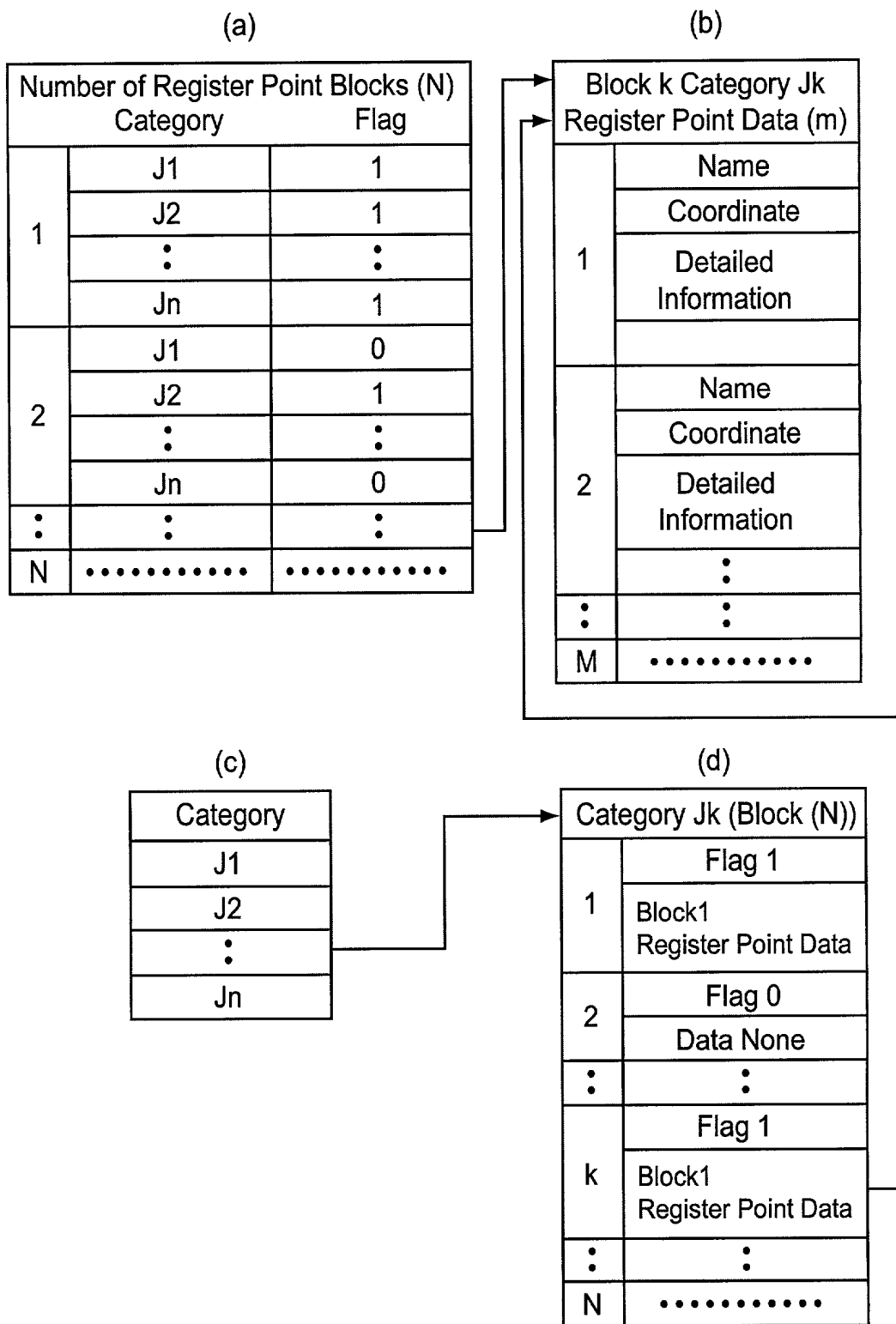


Fig. 9

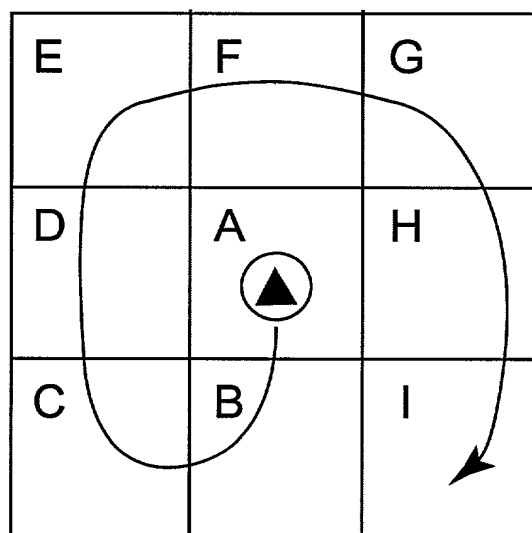


Fig. 10

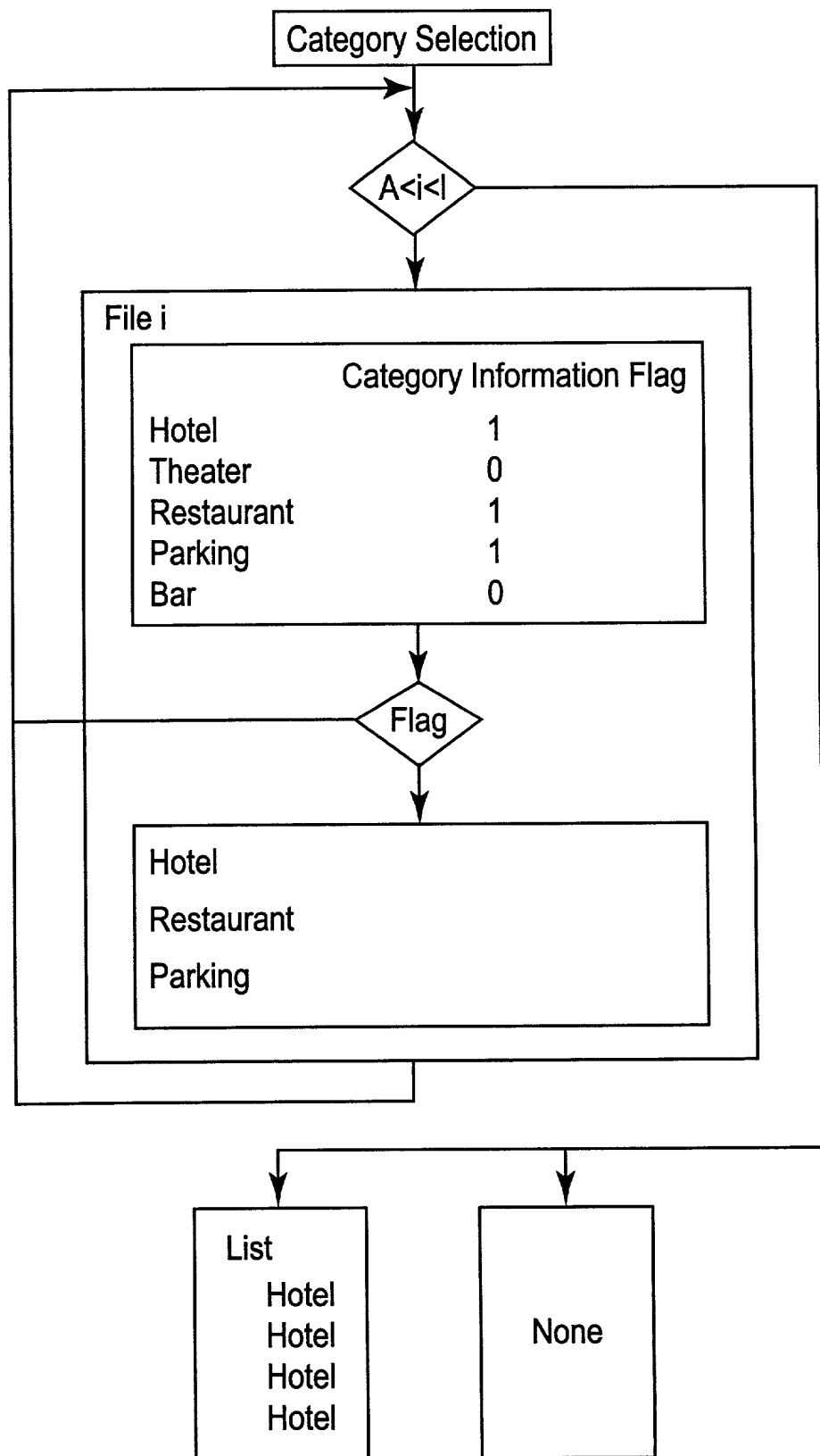


Fig.11



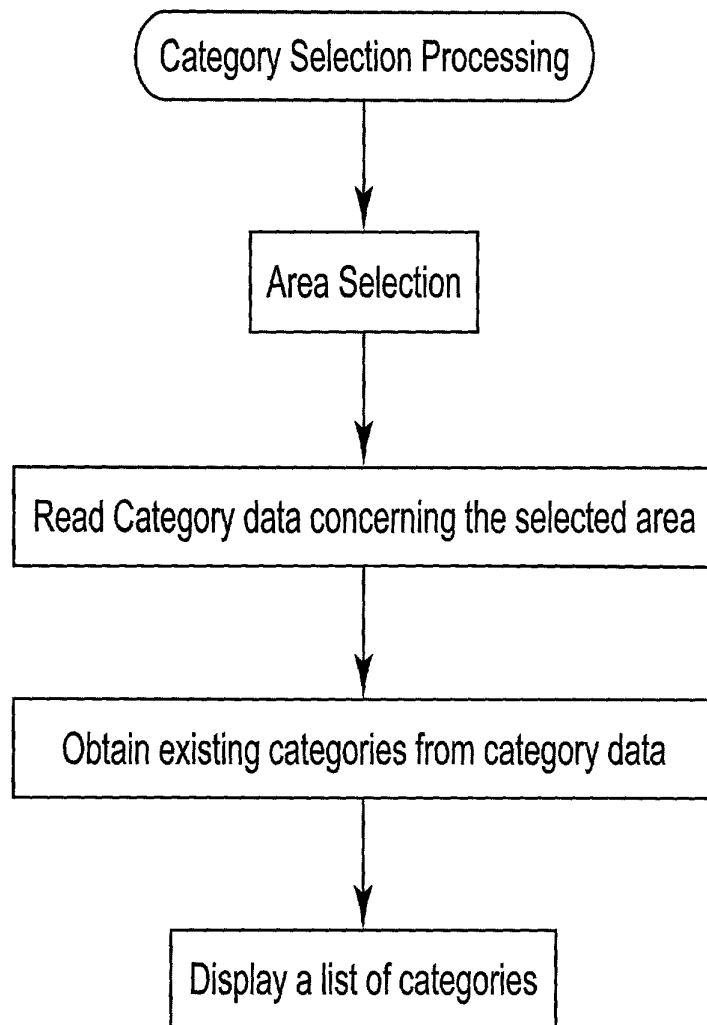


Fig.12

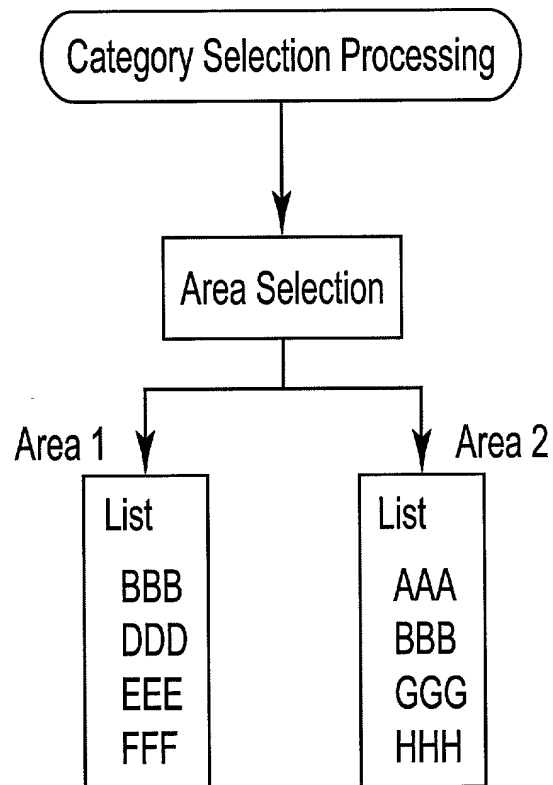


Fig. 13

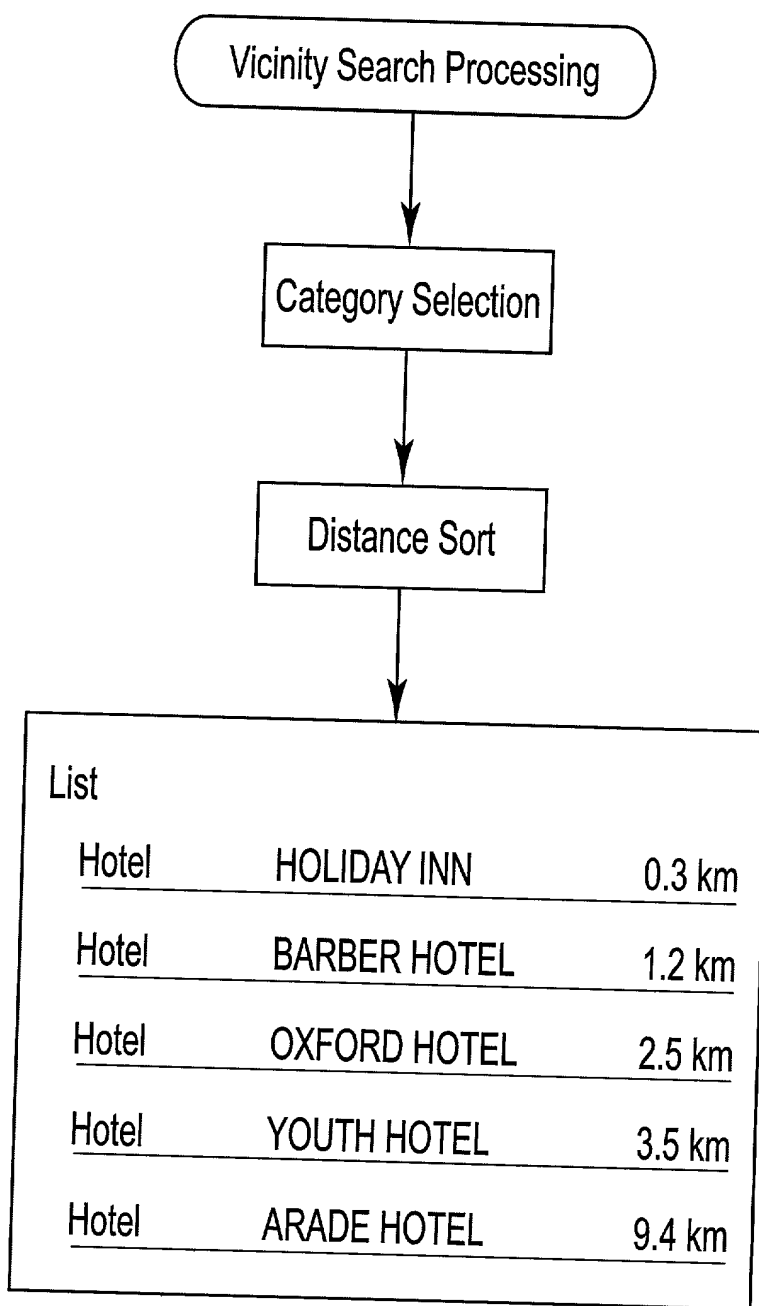


Fig. 14  
Related Art

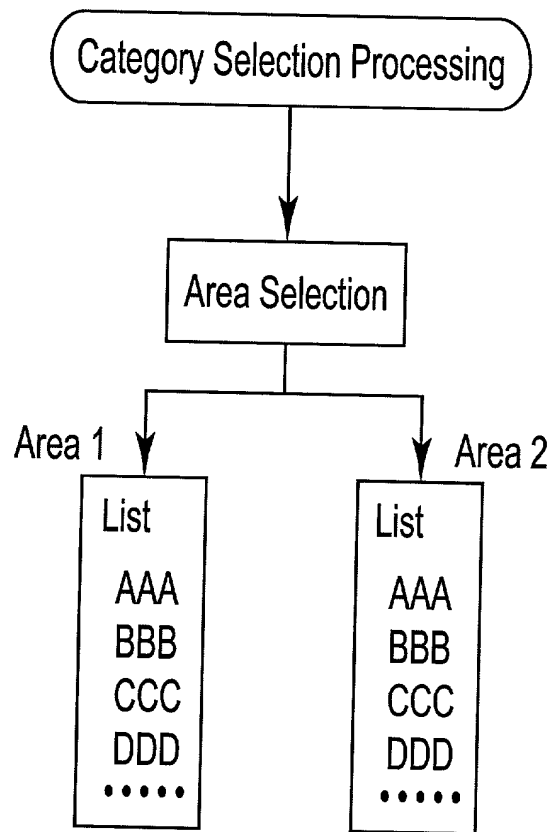


Fig. 15  
Related Art